* The ultrasonic sensor has 4 pins
* Power, ground, trigger and echo
* The way it works is by sending a 10us high signal to the trigger pin and then a high signal will arise in the echo pin which represents the time it took for the sensor to send an ultrasonic wave and receive it back
* The pulse that the echo pin sends is what should be measured using the timer module to get the time sound took to travel back and forth from the sensor to the object
* Then, to calculate the distance we use the formula